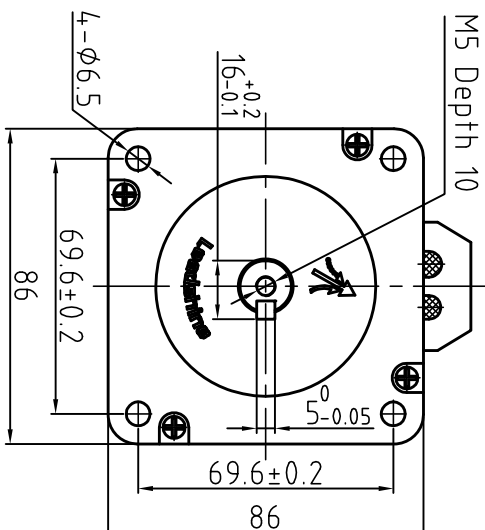
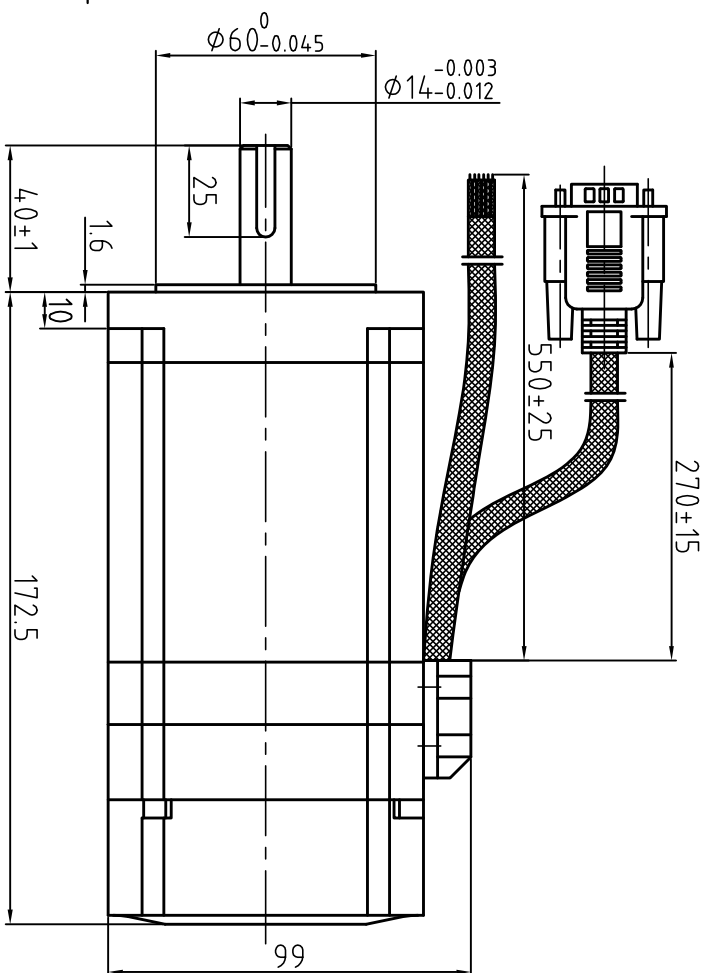
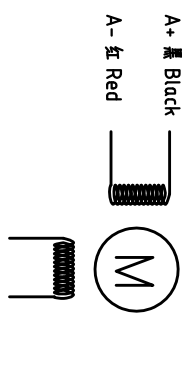


Dimension: (Unit: mm)

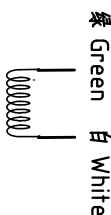


版本 Rev:	日期 Date:	变更文件号 ECU NO.	变更内容 Revisions	设计 By:
V1.0	17.11.8		插图	王洪松

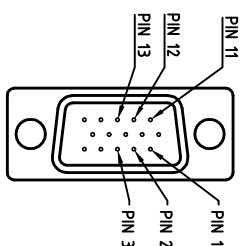
**Motor Connctions**



**Brake Connctions**



**Encoder Signals**



PIN	1	2	3	11	12	13
颜色	黑	红	白	黄	绿	蓝
定义	A+	VCC	GND	B+	B-	A-

**Common Rating**

Step angle	18°
Position accuracy	18±0.09°
Dielectric strength	1000VAC 1min
Insulation resistance	100MΩhm(500VDC)
Insulation class	B
Temp rise(Max)	80K
Radial play	Max:0.02mm(Load 450g)
Axial play	Max:0.08mm(Load 900g)

**Specification**

Current/phase	6.0 A
Voltage	3.2 V
DC Resistance/phase	±10% 0.53 Ω
Inductance/phase	±20% 3.9 mH
Holding torque	8 N·M
Inertia	2.8 kg·cm <sup>2</sup>
Weight	4 kg
Encoder Resolution	1000 cpr

**Brake Specification**

Voltage	24Vdc
Friction torque	4N·M

设计 Designed	王洪松	日期 Date	17.11.8	材料 Material	深圳市雷赛智能控制股份有限公司 SHENZHEN LEADSHINE TECHNOLOGY CO., LTD.	
审核 Checked	秦军	17.11.8	第一角画法 First Angle projection	混合伺服电机		
批准 Approved	田天胜	17.11.8	重量/Weight	比例/Scale	图例/Stage Mark	图号 DWG. NO.
图号 Part No.	共 1 套 第 1 套		Sheet	1 of 1	LS-CME86-04-0110-04	